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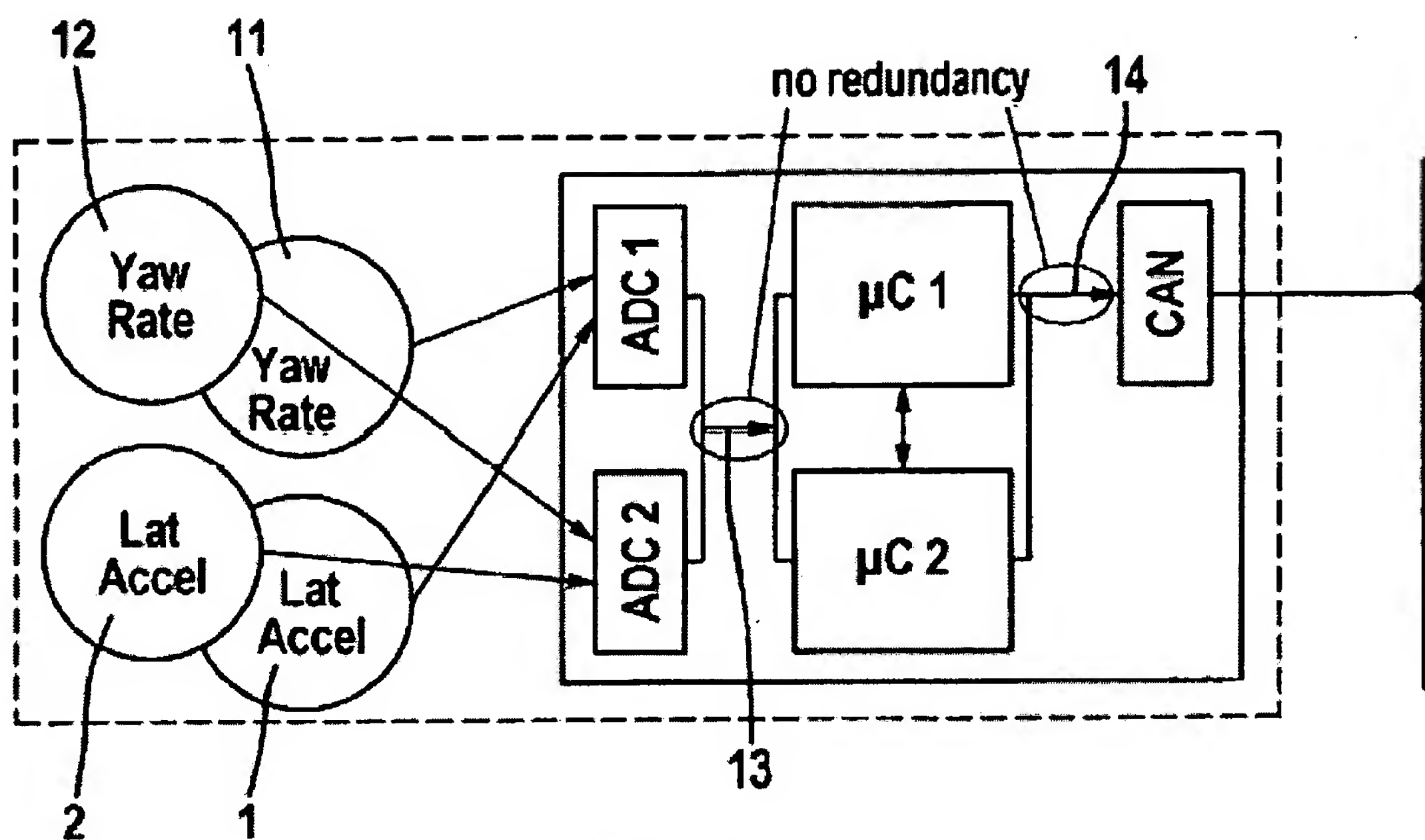


Fig. 1

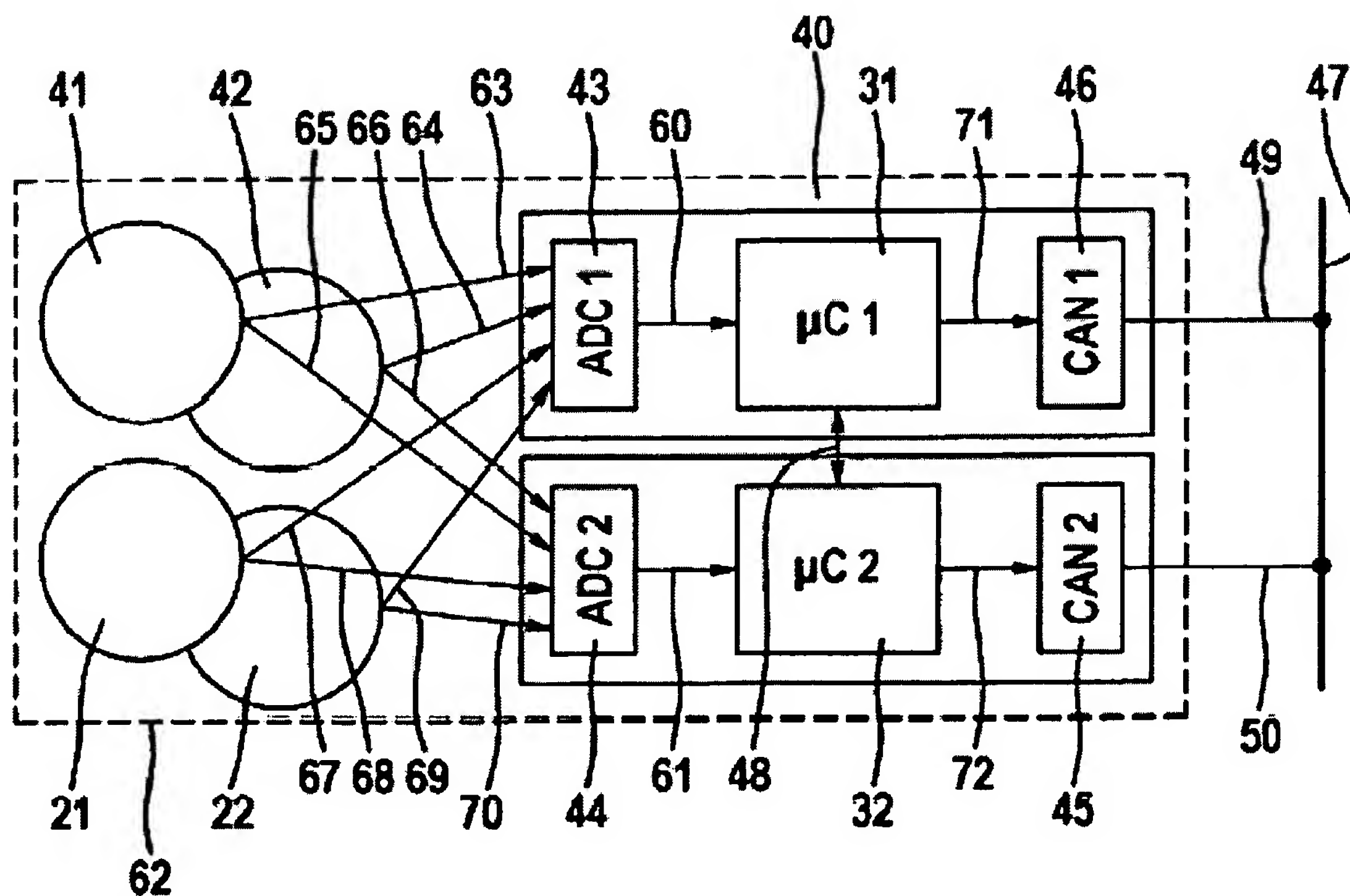


Fig. 4

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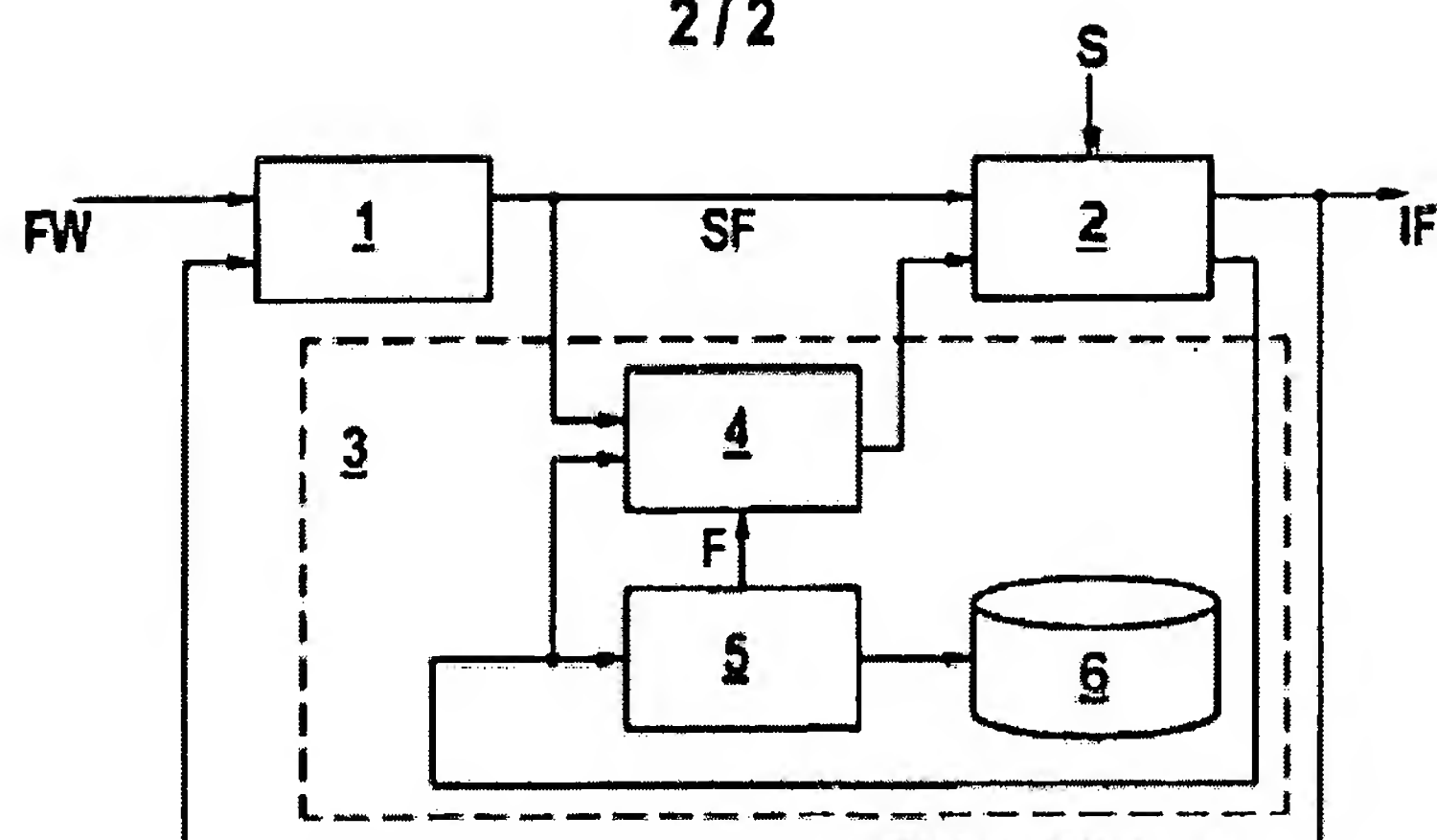


Fig. 2

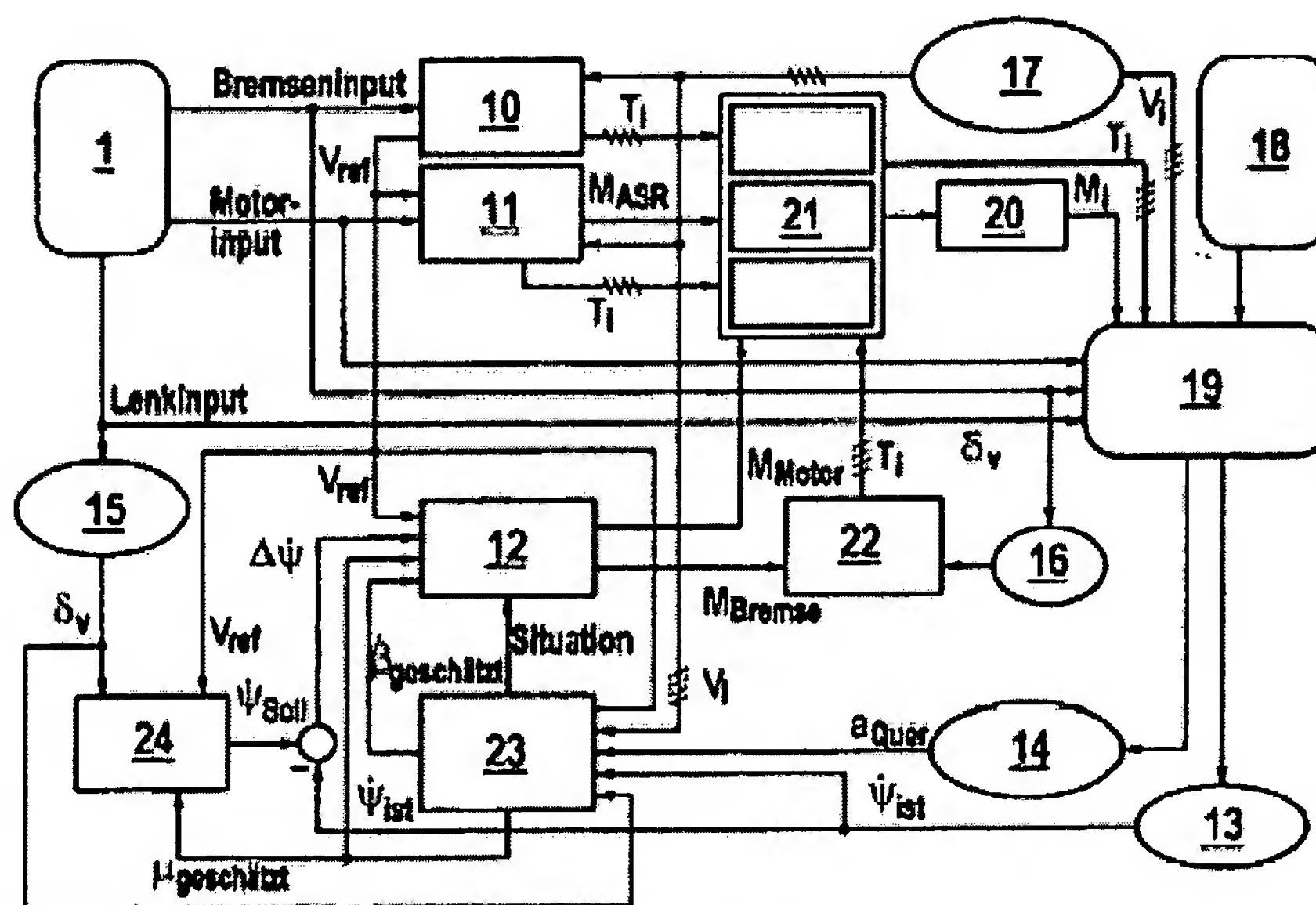


Fig. 3

Bremseninput	=	Brake input	Motor	=	Engine	Quer	=	Lateral
Motorinput	=	Engine input	Bremse	=	Brake	Soll	=	Theoretical
Lenkininput	=	Steering input	$\mu_{geschätzt}$	=	Estimated	ist	=	Actual